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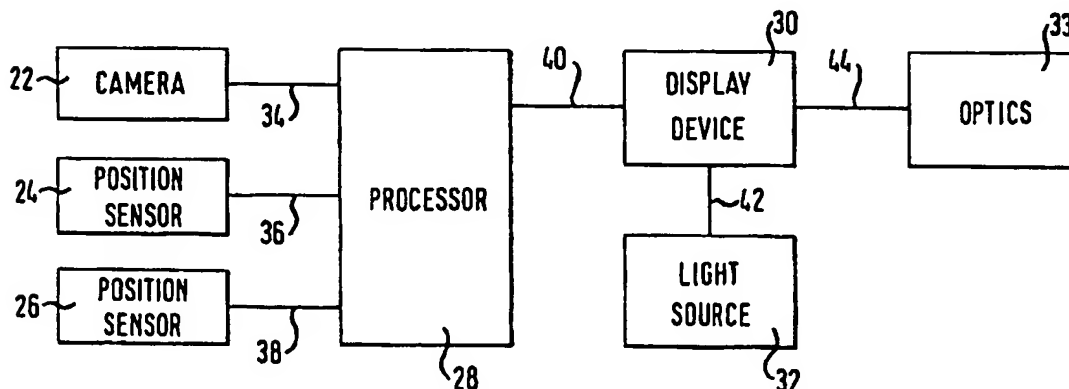
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02.08.95 Bulletin 95/31(72) Inventor: **Gove, Robert J.**
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D-81241 München (DE)(54) **Visual information system.**

(57) A visual information system to capture an input image using a camera 22, manipulate the image using processor 28, and project the processed image using optics 33 to superimpose the processed image on the actual object being observed by a viewer. Processing is done in real-time to allow the

viewer to see both the actual and processed images while the viewer moves and changes viewing angles. Areas of interest in the displayed image may be highlighted or include graphical information for the viewer.

FIG. 1
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1. FIELD OF THE INVENTION

This invention relates to the field of image processing systems, more particularly to head-mounted image processing and display systems.

2. BACKGROUND OF THE INVENTION

There are many instances when it is advantageous to use photographs or electronically stored images to aid a viewer in observing the features and spatial relationships of an object. The features the viewer would like to locate or see are sometimes obscured or are difficult to locate with the unaided eye.

One example is during a surgical procedure. A surgeon may take a photograph or an electronic image of an area before surgery begins. The image may be from previous diagnostic test such as magnetic resonance imaging (MRI) or computerized axial tomography (CAT). The surgeon will refer to this image during surgery as a guide for the procedure. For example, an image may be taken of a tumor before starting a removal procedure. During the procedure, the surgeon can refer back to the image to assist in locating the tumor or to ensure that the entire tumor has been removed.

SUMMARY OF THE INVENTION

The present invention provides a method and device for providing visual information to a viewer without blocking the vision of the viewer or requiring the viewer to look away from the object of interest. One embodiment of the invention to provide an imaging system that displays a computer generated image in the field of view of the user, without obstructing the view of the user. This allows the user to see the image without looking away from the object of interest. Furthermore, the image the user sees will be manipulated to have the correct perspective or viewpoint. The computer generated image may be superimposed on the actual image that the user sees to help the user correlate information from the computer generated image with the users actual view of the object.

It is a further advantage of the invention that the movement of the user or object can be monitored by the system and the displayed images changed to compensate for the movement. This allows the user to see the object from different perspectives by simply moving his head. This three dimensional effect is important in that the image may show internal features that may not be visible by the user. For example, during a surgical procedure locations of major arteries can be marked to allow the surgeon to avoid them.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a schematic view of one embodiment of a visual information system.

FIG. 2 is a schematic view of a first embodiment of a display mechanism of the visual information system.

FIG. 3 is a pictorial view of a second embodiment of a display mechanism of the visual information system.

FIG. 4 is a pictorial view of one embodiment of the visual information system.

FIG. 5 is a pictorial view of a patients hand as seen through one embodiment of the disclosed visual information system.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

There are several drawbacks associated with using stored images to assist a viewer in identifying objects in his view. First, the viewer must look away from the object of interest in order to see the stored images, interrupting the work being performed and breaking the viewers concentration. Second, the images presented to the viewer have a fixed perspective, that is the viewer cannot usually manipulate the viewpoint of the image. Depending on the circumstances, the image may be difficult to correlate with the perspective of the viewer. For example, when testing an electronic assembly, the image of a component to be probed or removed may not be of much help when the component is surrounded by a large number of very similar, or worse yet, identical components.

A much better solution is to superimpose the image on the object being viewed, in effect highlighting the features of interest in the object. There are many applications for the vision enhancement imaging system disclosed, for example, three dimensional information from the images used to guide the surgical procedure discussed above could be used to generate enhanced images and projected into the line of sight of the surgeon to allow the surgeon to see the images without having to look away from the patient.

Figure 1 shows a schematic view of one embodiment of the disclosed imaging system. The video camera 22 monitors the subject, in this case a surgery patient, and transmits an electronic representation of the image to the processor 28 via channel 34. The choice of video camera depends on the information required and is not critical to the invention. For example, the camera could be monochrome or color, digital or analog, and could be receptive to light outside the visible spectrum. In some applications it may be advantageous to have more than one camera to provide the processor

with additional perspectives to aid in the generation of three-dimensional images.

Optional patient position sensor 24 transmits information to the processor 28 to allow the image processing and display functions to compensate for patient motion. Note that the object position and motion information can be extracted from the image obtained via the camera and the use of vision algorithms. The processor 28 may determine position and motion information by tracking features of the patient. If no suitable features exist naturally on the patient, high contrast marks could be drawn on the patient prior to beginning a procedure to allow the patient to be tracked optically by the processor 28.

Viewer position sensor 26 tracks the position of the viewer to allow the viewer to move or turn to see different views of an image. Not only does the position sensor 26 allow the processor 28 to compensate for the viewing angle, it allows the processor 28 to scale the image as the distance from the object to the viewer changes and to move the image across the screen as the viewer scans the object. If the initial positions of the viewer and object are known, then motion sensors may be used instead of position sensors. Motion compensation prevents images from being warped or smeared as the patient moves.

The processor 28 applies image processing algorithms to manipulate the image from the camera 22 and other image sources. The other sources are not shown in Figure 1, but could include scanned photographs, MRI or CAT scans, other medical diagnostic equipment, prior surgical procedures, or any image device. Image processing functions that would be desirable in some applications are image conditioning, feature extraction, and matching or correlation algorithms. The computer generated images may be wire-frame representations or fully rendered three-dimensional images or a hybrid combination of the two. For example, a tumor may be fully rendered and colorized while the surrounding tissue is represented by a wire-frame model. The processor could also use false coloring to highlight certain features or objects. Textual data may also be displayed to inform the surgeon of the patients vital signs, duration of surgery, etc.

In addition to manipulating the image data, the processor 28 may also receive inputs from the surgeon to allow the surgeon to mark areas of interest and to build a graphical database for later analysis. Inputs from the surgeon could also be used with stored information to aid feature recognition. The surgeon could use any available means to input data into the processor including a keyboard, mouse, touch screen, trackball, light pen, or voice recognition.

Processor 28 can be any type of processor or group of processors capable of performing the necessary image processing and display control functions required of the imaging system. For example, the processor could be designed around the Texas Instruments Multimedia Video Processor (MVP) image processing chip. The processor should have sufficient through-put to process the images, object motion, viewer position, and viewer input data in real-time. The required frame rate will vary depending on the application but should preferably be in the range of 60 to 100 frames per second, although 30 or fewer frames per second may be acceptable in some circumstances, especially situations with very little movement. The frame rate may be dynamically varied as image complexity and image processing algorithms vary the demands on processing power.

The processed images are sent to the display device 30 via display control bus 40. The display device could be any type of spatial light modulator capable of displaying an image such that it appears superimposed on an object being viewed. Optics 33 are used as required to focus and project the image. Light source 32 and optics 33 may not be required in all applications depending on the type of spatial light modulator used.

One embodiment of a display system 68 comprising the display device, light-source, and optics is shown in Figure 2. Light from source 54 is focused and collimated as necessary by lens 58. The focused light 56 is modulated by a spatial light modulator, in this case a DMD array 60. The reflected light 62 is focused and magnified as necessary by lens 64. The light is then reflected off of the lens 50. At the same time, light 48 from the object 46 is allowed to pass through the lens 50. The light 52 from the object and the DMD array exits the display system 68 and is seen by the viewer.

The lens 50 may be worn like a pair of goggles, or a face shield, to allow the viewer to see the object 46 through the lens 50 and also see the image projected onto the lens. Lens 50 may be partially silvered to reflect light or may simply be any material with a partially reflective surface. Lens 50 is typically designed to allow approximately 90% of the light from the object to pass through the lens 50 while reflecting 10% of the reflected light 66 from the DMD. The amount of light reflected and transmitted by lens 50 depends on the application and the amount of light available from the object and the imager. The DMD 60 is particularly useful for this applications because it allows the brightness of the projected image to be adjusted over a wide range. This wide adjustment allows the viewer to strike an acceptable balance between image brightness and object visibility.

A second embodiment of a display system according to the present invention simply attenuates light from the object of interest. This second embodiment, shown in Figure 3, may use a liquid crystal display (LCD) instead of a DMD. Because no light source or projection optics are required, the LCD 67 may be the actual lens of the goggles 69 worn by the viewer. Cable 71 carries the signals necessary to operate the LCD. The use of an LCD instead of the reflective lens of Figure 2 attenuates more of the light from the image and reduces the visibility of the viewer. Areas of interest may be marked by attenuating light from the areas of interest, or by attenuating light from all areas except those of interest.

A pictorial view of one embodiment of the surgical imaging system is shown in Figure 4. Viewer 72 looks through display system 68 at the object 46. In this embodiment both the display system 68 and the viewer position sensor 26 are head mounted on the viewer 72. Object position sensor 24 is attached to the object 46 without obstructing the view of either the viewer 72 or the camera 22. Processor 28 receives data from the camera 22, the viewer position sensor 26, and the object position sensor 24 and sends data to the display system 68.

Figure 5 shows one example of the view through the imaging system during an operation to remove a foreign object from a patient. In Figure 5 a surgeon is attempting to remove a foreign object 80 from a patient's hand 82. Textual information 84, such as the patient's vital signs, distances between objects, and elapsed time may be displayed. Objects of concern, in this case a nerve 86 that the surgeon is attempting to avoid, and the entrance path 88 of the object 80, may be highlighted. It should be appreciated that as the surgeon moves in relation to the patient, the perspective of the displayed image and the patient's hand will change in unison allowing the surgeon to determine the best method of removing the object 80.

Thus, although there has been disclosed to this point a particular embodiment for a surgical imaging system, it is not intended that such specific references be considered as limitations upon the scope of this invention except in-so-far as set forth in the following claims. Furthermore, having described the invention in connection with certain specific embodiments thereof, it is to be understood that further modifications may now suggest themselves to those skilled in the art, it is intended to cover all such modifications as fall within the scope of the appended claims.

Claims

1. An imaging system comprising:
 - a camera to monitor a scene in order to convert scene information into electronic signals, and to transmit said signals;
 - a processor to receive said signals from said camera, and to perform image processing routines on said signals, and to generate processed signals representing information about said scene; and
 - a display device to receive said processed signals and to convert said processed signals into a displayed image, wherein a viewer may look through said display device and see both said scene and said displayed image.
2. The imaging system of claim 1, wherein said displayed image is superimposed on said scene from the perspective of said viewer.
3. The imaging system of claim 1, wherein said displayed image is projected onto the lens of a pair of goggles.
4. The imaging system of claim 1, wherein said displayed image is projected onto a face shield.
5. The imaging system of claim 1 wherein said display device comprises a spatial light modulator, wherein said viewer looks through said spatial light modulator.
6. The imaging system of claim 1 wherein said display device comprises a digital micromirror device.
7. The imaging system of claim 1 wherein said display device comprises a liquid crystal display.
8. The imaging system of claim 1 wherein said display device comprises a partially silvered lens.
9. The imaging system of claim 1, wherein said display device is head-mounted on the user of said system.
10. The imaging system of claim 1, wherein said processor performs said image processing routines in real-time.
11. The imaging system of claim 1, wherein said processor tracks features of said scene such that motion in said scene is compensated.

12. The imaging system of claim 1, further comprising a position sensor attached to an object in said scene and in communication with said processor to allow said processor to monitor the position of said object in said scene. 5
13. The imaging system of claim 1, further comprising a motion sensor attached to an object in said scene and in communication with said processor to allow said processor to compensate for motion of said object within said scene. 10
14. The imaging system of claim 1, further comprising a position sensor attached to said user and in communication with said processor to allow said processor to compensate for movement of said user. 15
15. The imaging system of claim 1, further comprising a motion sensor attached to said user and in communication with said processor to allow said processor to compensate for movement of said user. 20
16. The imaging system of claim 1, wherein said displayed image is a high-contrast picture of said scene. 25
17. The imaging system of claim 1, wherein said displayed image is a false-color representation of a portion of said scene. 30
18. An imaging system comprising:
- a camera to constantly monitor a scene and convert scene information to electronic signals; 35
 - a processor to receive said electronic signals and perform image processing routines on said electronic signals and to output a processed video signal; 40
 - a position sensor attached to an object in said scene to communicate information concerning the position of said object to said processor; 45
 - a position sensor attached to a user of said system to communicate information concerning the position of said user to said processor; 50
 - a display device to receive said video signal and to convert said video signal into a display image, wherein a viewer may look through said display device and see the display image superimposed on said scene. 55
19. A method of displaying an image of an object comprising:
- converting light from an object to electronic signals using a camera;
 - tracking the position of said object;
 - tracking the position of a viewer;
 - processing said electronic signals to compensate for the relative position of said object and said viewer;
 - converting said processed electronic signals into an image; and
 - displaying said image such that said viewer sees said image superimposed on said object.
20. The method of claim 15 wherein tracking the position of said object using a position sensor is replaced with tracking the motion of said object with a motion sensor.
21. The method of claim 15 wherein tracking the position of said viewer using a position sensor is replaced with tracking the motion of said viewer with a motion sensor.

FIG. 1

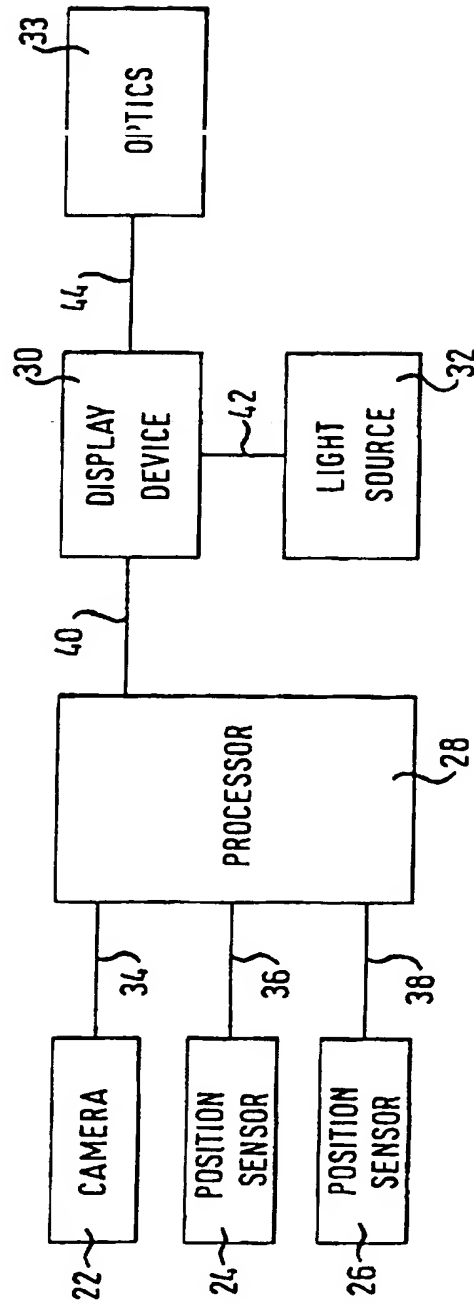


FIG. 2

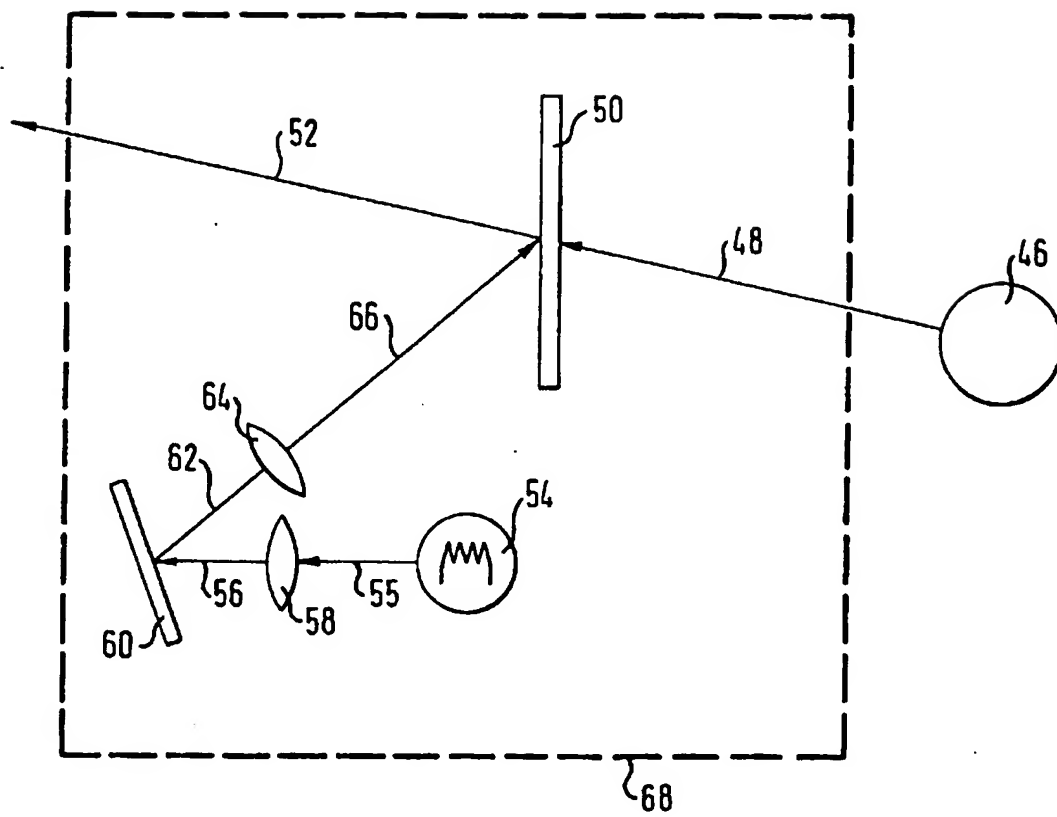


FIG. 3

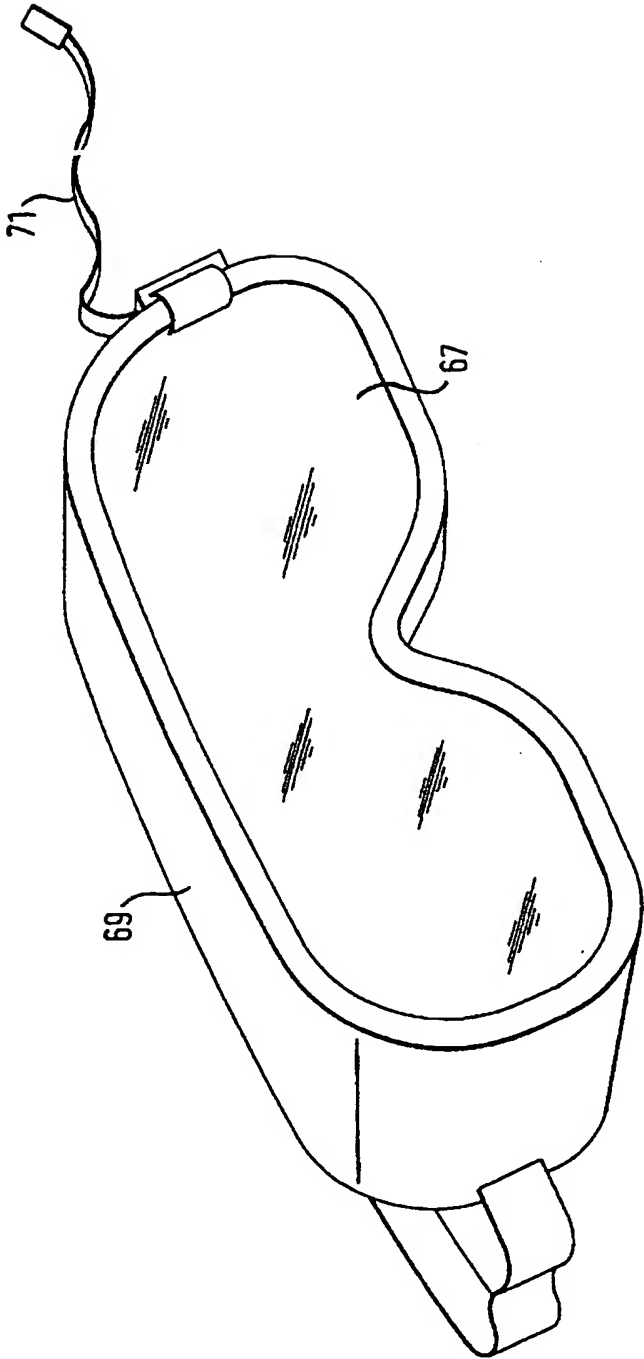


FIG. 4

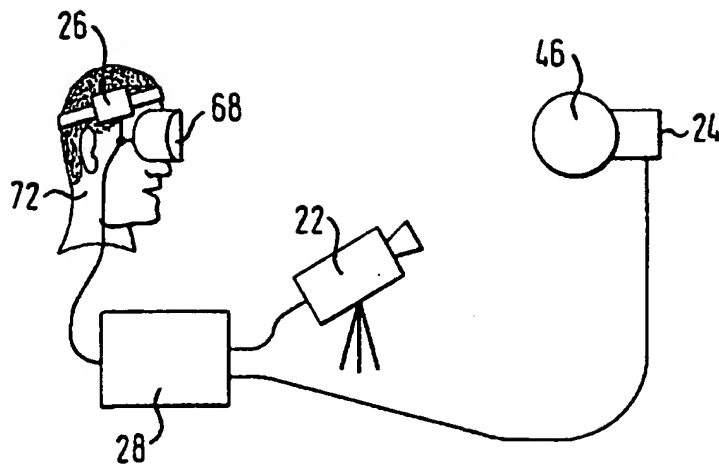
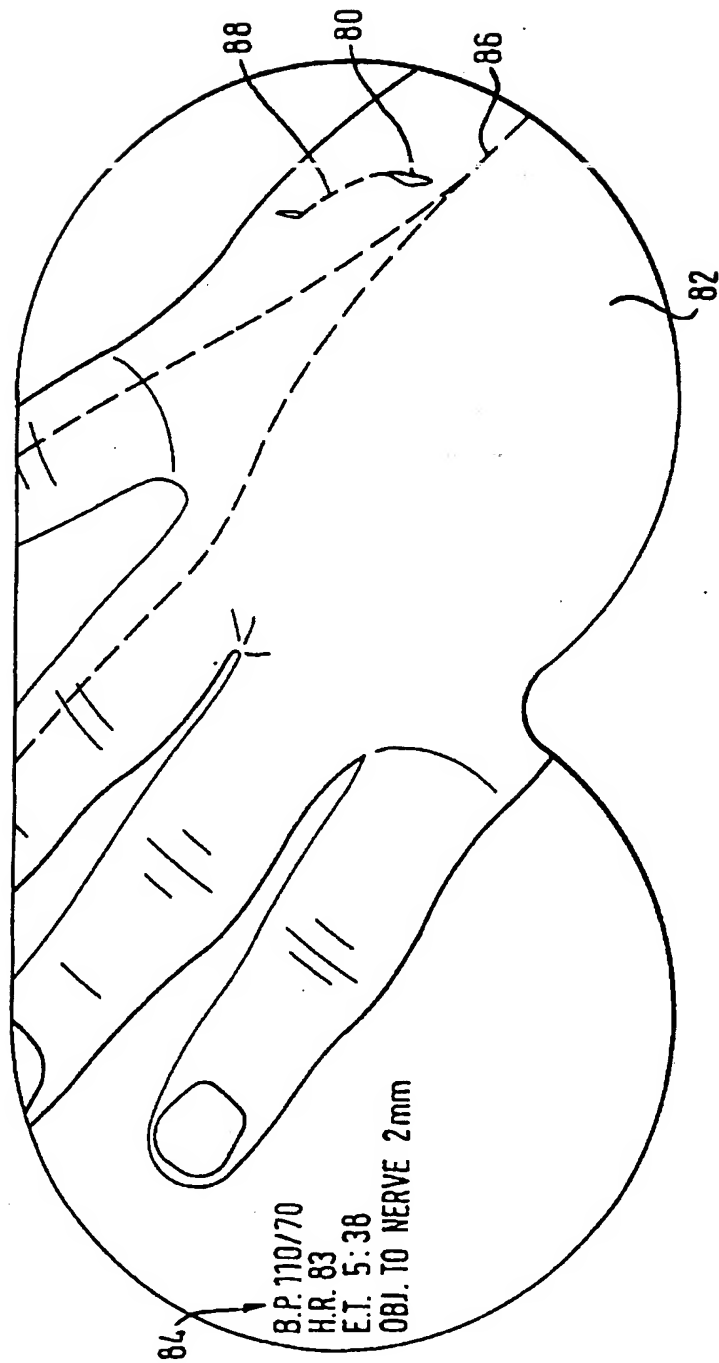
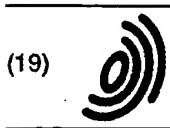


FIG. 5





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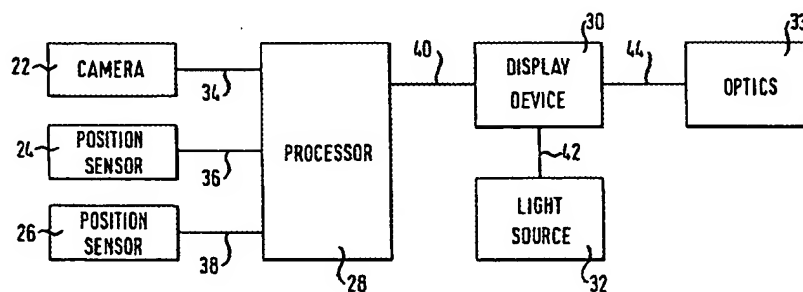
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(54) **Visual information system**

(57) A visual information system to capture an input image using a camera 22, manipulate the image using processor 28, and project the processed image using optics 33 to superimpose the processed image on the actual object being observed by a viewer. Processing is done in real-time to allow the viewer to see both the

actual and processed images while the viewer moves and changes viewing angles. Areas of interest in the displayed image may be highlighted or include graphical information for the viewer.

FIG. 1



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EUROPEAN SEARCH REPORT

Application Number
EP 94 11 9066

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.Cl.6)
X	US 5 164 721 A (HAMILTON BRUCE E ET AL)	1,2,4,9,10,14,15	H04N5/232 A61B19/00 G02B27/01
Y	* column 8, line 58 - line 65 * * column 9, line 45 - line 63 * * column 10, line 32 - line 35 * * column 11, line 19 - line 29 * * column 14, line 26 - line 31 * * column 14, line 52 - line 59 *	3,5-8,16	
Y	DE 92 17 643 U (SIWOFF RONALD) * page 7, line 8 - line 17 * * page 9, line 14 - line 24 * * page 38, line 16 - line 19 * * page 46, line 9 - line 11 *	3,5,7,16	
Y	EP 0 391 529 A (TEXAS INSTRUMENTS INC) * column 6, line 39 - line 45 *	5,6	
Y	EP 0 065 578 A (TEINZER HARALD) * page 1, line 25 - line 30 *	7,8	TECHNICAL FIELDS SEARCHED (Int.Cl.6)
A	COMPUTER GRAPHICS, vol. 26, no. 2, 2 July 1992, USA, pages 203-210, XP002045387 BAJURA M, FUCHS H, OHBUCHI R: "merging virtual objects with the real world: seeing ultrasound imagery within the patient" * page 205, right-hand column, paragraph 6 * * page 206, left-hand column, paragraph 2 * * page 206, right-hand column, paragraph 3 - paragraph 6 *	1,2,12,14	G02B H04N
The present search report has been drawn up for all claims.			
Place of search THE HAGUE		Date of completion of the search 31 October 1997	Examiner Sindic, G
<p>CATEGORY OF CITED DOCUMENTS</p> <p>X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document</p> <p>T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons A : member of the same patent family, corresponding document</p>			

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European Patent Office

CLAIMS INCURRING FEES

The present European patent application comprised at the time of filing more than ten claims

- ☐ All claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for all claims.
- ☐ Only part of the claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims and those claims for which fees have been
namely claims:
- ☐ No claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims.

LACK OF UNITY OF INVENTION

The Search Division considers that the present European patent application does not comply with the requirement of the unity of the invention and relates to several inventions or groups of inventions, namely:

See Sheet B

- ☐ All further search fees have been paid within the fixed time limit. The present European search report has been drawn up for all claims
- ☐ Only part of the further claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the inventions in respects of which search fees have been paid,
namely claims:
- ☒ None of the further claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the invention first mentioned in the claims,
namely claims: 1 - 10 , 14 - 17



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**LACK OF UNITY OF INVENTION
SHEET B**

Application Number

EP 94 11 9866

The Search Division considers that the present European patent application does not comply with the requirements of unity of invention and relates to several inventions or groups of inventions, namely:

1. Claims: 1-10, 14-17

Imaging system comprising a display providing visual information to a viewer without blocking his vision or requiring to look away from a scene.

2. Claims: 11-13, 18-21

Imaging system and method having scene feature tracking and object motion compensation capabilities.

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